LLVM Berlin Meetup

Auto-tuning Compiler Transformations with Machine Learning

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Outline

- Why automatic tuning
- Auto-tuning with machine learning
  - Four challenges
- Auto-tuning by example
  - Classification, for heterogenous task partitioning
  - Regression, for vectorization cost model
  - Ordinal regression, for stencil computations
- Conclusion
  - Auto-tuning and programming models
  - Importance of structural approaches
Why Automatic Tuning (1)

- Simple example: loop unrolling

```java
for(int i=0;i<1000;i++){
    a[i] = b[i] + c[i];
}
```

```java
for(int i=0;i<1000;i+=2){
    a[i] = b[i] + c[i];
    a[i+1] = b[i+1] + c[i+1];
}
```

unroll factor 2

- What is the best loop unrolling factor?
  - Transformation space is small
  - Prediction is still challenging

Mark Stephenson, Saman P. Amarasinghe:
Predicting Unroll Factors Using Supervised Classification. CGO 2005: 123-134
Why Automatic Tuning (2)

- Example: six-point von Neumann stencil

```c
for(int t=1; t<nt; t++)
    for(int x=0; x<nx; x++)
        for(int y=0; y<ny; y++)
            for(int z=0; z<nz; z++)
            {
                out[x,y,z; t] =
                    in[x-1,y,z; t-1] + in[x,y+1,z; t-1] +
                    in[x+1,y,z; t-1] + in[x,y,z-1; t-1] +
                    in[x,y-1,z; t-1] + in[x,y,z+1; t-1];
            }
```

For each time step \( t \)

For each cell \((x, y, z)\)

One write: the element \((x, y, z)\) at time \( t \)

We call the read-point pattern stencil shape

Some stencils have reads on older time steps: \( t-2, t-3, \ldots \)
Why Automatic Tuning (3)

- Stencil computation

```c
for(int t=1; t<nt; t++)
for(int x=0; x<nx; x++)
    for(int y=0; y<ny; y++)
        for(int z=0; z<nz; z++)
        {
            out[x,y,z; t] =
                in[x-1,y,z; t-1] + in[x,y+1,z; t-1] +
                in[x+1,y,z; t-1] + in[x,y,z-1; t-1] +
                in[x,y-1,z; t-1] + in[x,y,z+1; t-1];
        }
```

- Transformation space is large (~16K configurations) and complex (i.e., with discontinuities)

Autotuning Stencil Computations with Structural Ordinal Regression Learning.
Cosenza, Durillo, Ermon, Juurlink. IPDPS 2017
### Why Automatic Tuning (4)

<table>
<thead>
<tr>
<th>Project</th>
<th>Benchmark</th>
<th>Possible configurations</th>
</tr>
</thead>
<tbody>
<tr>
<td>PetaBricks</td>
<td>Poisson</td>
<td>$10^{3657}$</td>
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<tr>
<td>gcc/g++ flags</td>
<td>all</td>
<td>$10^{806}$</td>
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<tr>
<td>Halide</td>
<td>Bilateral</td>
<td>$10^{176}$</td>
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<td>PetaBricks</td>
<td>Sort</td>
<td>$10^{90}$</td>
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<tr>
<td>Halide</td>
<td>Blur</td>
<td>$10^{25}$</td>
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<tr>
<td>Unitary</td>
<td>n/a</td>
<td>$10^{21}$</td>
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<tr>
<td>Stencil/OpenTuner</td>
<td>all</td>
<td>$10^{6.5}$</td>
</tr>
<tr>
<td>Stencil/Patus*</td>
<td>all</td>
<td>$10^{4}$</td>
</tr>
</tbody>
</table>

*PetaBricks: A Language and Compiler for Algorithmic Choice.*
Ansel, Chan, Wong, Olszewski, Zhao, Edelman, Amarasinghe. PLDI 2009

*OpenTuner: An Extensible Framework for Program Autotuning.*
Ansel, Kamil, Veeramachaneni, Ragan-Kelley, Bosboom, O'Reilly, Amarasinghe. PACT 2014

*Halide: A Language and Compiler for Optimizing Parallelism, Locality, and Recomputation in Image Processing Pipelines.*
Desiderata for Automatic Tuning

- Ideally, we would like to have autotuners that are
  - Fast, to be integrated into common compilers
  - Accurate, to deliver good, close-to-peak solutions
  - Flexible, to adapt to any possible input problem
  - Portable, to target any hardware

- Traditional approaches
  - Analytical model
    - generic, but hard to build, require domain expertise
    - far from peak performance
  - Iterative-compilation with search heuristics
    - accurate solution, but long compilation time
    - heuristics: genetic algorithms, differential evolution, ...
Autotuning with Machine Learning

- **Autotuning with Machine Learning**: *Supervised Machine Learning*
  - Build a model in a preprocessing stage, later reuse the model for a new input
  - **Fast**: can be used in **compilers** (i.e., fast compilation time)
  - **Portable**: just build a new model for a new hardware/platform

- **Machine learning is already successful in different fields**
  - Image recognition, speech recognition, NLP

- **However**
  - Compilers and software optimization present some **unique challenges**
  - Existing methods do not apply so well
    - Too little data for deep neural networks
    - Training data has different structure

  **We need** fundamentally new approaches
Autotuning with Supervised Learning

Tuning problem

<table>
<thead>
<tr>
<th>input instances</th>
<th>tuning configurations</th>
</tr>
</thead>
<tbody>
<tr>
<td>( (a_1 \ldots a_s) )</td>
<td>( (t_{1,1} \ldots t_{1,m}) )</td>
</tr>
<tr>
<td>( (t_{2,1} \ldots t_{2,m}) )</td>
<td>( \ldots )</td>
</tr>
<tr>
<td>( \ldots )</td>
<td>( \ldots )</td>
</tr>
<tr>
<td>( (t_{n,1} \ldots t_{n,m}) )</td>
<td>( \ldots )</td>
</tr>
</tbody>
</table>

encoding

training phase

<table>
<thead>
<tr>
<th>training dataset</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \ldots )</td>
</tr>
<tr>
<td>( \ldots )</td>
</tr>
<tr>
<td>( \ldots )</td>
</tr>
<tr>
<td>( \ldots )</td>
</tr>
</tbody>
</table>

model

execution/compilation phase

<table>
<thead>
<tr>
<th>new input instance</th>
<th>tuning configurations</th>
</tr>
</thead>
<tbody>
<tr>
<td>( (k_1 \ldots k_s) )</td>
<td>( (t_{1,1} \ldots t_{1,m}) )</td>
</tr>
<tr>
<td>( (t_{2,1} \ldots t_{2,m}) )</td>
<td>( \ldots )</td>
</tr>
<tr>
<td>( \ldots )</td>
<td>( \ldots )</td>
</tr>
<tr>
<td>( (t_{n,1} \ldots t_{n,m}) )</td>
<td>( \ldots )</td>
</tr>
</tbody>
</table>
Four Research Aspects of ML-based Autotuning

Better problem-specific encoding
- tree
- graph
- polyhedron

More & better training data
- synthetic code generation
- space pruning

Tuning problem

Input instances

Tuning configurations

Encoding

(a_1 \ldots a_s)

(t_{1,1} \ldots t_{1,m})

(t_{2,1} \ldots t_{2,m})

(\ldots)

(t_{n,1} \ldots t_{n,m})

(b_1 \ldots b_s)

(t_{1,1} \ldots t_{1,m})

(t_{2,1} \ldots t_{2,m})

(\ldots)

(t_{n,1} \ldots t_{n,m})

Training dataset

Model

Applications
- compiler transformations
- Domain Specific Language
- high-level application tuning

Better modeling
- structural learning
Autotuning by Example

- Three examples
  - Working on real compiler infrastructure
  - Using different modeling
  - Tuning different compiler transformations

1. Classification
   - For automatic task partitioning

2. Regression
   - For vectorization cost model in LLVM

3. Ordinal Regression
   - For stencil tuning computations
Automatic Heterogenous Task Partitioning

- Problem: Task Partitioning on Heterogenous Device
  - Hardware: One multi-core CPU, two GPUs
  - Where do run partition our OpenCL task?

Code: linear regression kernel
Hardware: CPU AMD 2x Opteron 6168 + 2x Radeon HD 5870

same hardware, same code, different size
Automatic Heterogenous Task Partitioning

- Problem: Task Partitioning on Heterogenous Device

Code: linear regression kernel

Hardware: CPU AMD 2x Opteron 6168 + 2x Radeon HD 5870

Code: reduction kernel

Hardware: CPU AMD 2x Opteron 6168 + 2x Radeon HD 5870

*same hardware, different code, same size*
Automatic Heterogenous Task Partitioning

- Problem: Task Partitioning on Heterogenous Device

Code: linear regression kernel

Hardware: CPU AMD 2x Opteron 6168 + 2x Radeon HD 5870

Hardware: CPU Intel 2x Xeon X5650 + 2x NVIDIA GeForce GTX480

different hardware, same code, same size
Automatic Heterogenous Task Partitioning

- Difficult problem
  - Depends on the code, the hardware and the (input) size
- What about heterogenous partitioning?
  - Support hybrid partitioning
  - Example: 20% on CPU, 40% on GPU1, 40% on GPU2
- Solution: machine learning
  - Training phase: build a partitioning model for a specific hardware
  - Deployment phase: infer the model to select the best-performing partitioning
Automatic Task Partitioning: Modeling

- Partitioning as classification
  - Classes are partitioning, e.g.
    - (20,40,40) means 20% CPU, 40% each GPU
    - (100,0,0) CPU only
    - (0,0,100) one GPU
    - (0,50,50) two GPUs
  - Overall 21 classes

- Classification algorithms
  - Support Vector Machine (SVM)
  - Artificial Neural Network (ANN)
Automatic Task Partitioning: Features

- 24 **static** features extracted from INSPIRE
  - INSieme Parallel Intermediate Representation
  - Examples: # of builtin, # of branches, # of scalar float op., # of vector float op.
- 9 **dynamic** features extracted at runtime
  - Examples: number of global work items, read and write buffer size
- **PCA** on static features
- Training on 23 test programs, each executed with different sizes
- Compiler infrastructure
  - Insieeme compiler with OpenCL frontend / backend
  - Currently reproducing on SYCL with a LLVM-based compilation infrastructure

An Automatic Input-Sensitive Approach for Heterogeneous Task Partitioning. Kofler, Grasso, Cosenza, Fahringer. ACM ICS 2013
Automatic Task Partitioning: Results

- **86% accuracy** (ANN + PCA) on $mc_1$, leave-one-out cross validation

- **88% accuracy** (ANN + PCA) on $mc_2$, leave-one-out cross validation
### Feature Analysis with Greedy Feature Selection

- **Portable** approach: different platforms exploit different features

<table>
<thead>
<tr>
<th>Rank</th>
<th>Static program features</th>
<th>MSE</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>OpenCL built-in functions</td>
<td>76.3</td>
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<tr>
<td>3</td>
<td>Number of branches / number of statements</td>
<td>64.4</td>
</tr>
<tr>
<td>4</td>
<td>Scalar float operations /number of statements</td>
<td>61.1</td>
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<table>
<thead>
<tr>
<th>Rank</th>
<th>Dynamic runtime features</th>
<th>MSE</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Data transfer size for splittable buffer (device to host)</td>
<td>99.7</td>
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<tr>
<td>5</td>
<td>Number of global work items</td>
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<td>6</td>
<td>Data transfer size for splittable buffer (host to device)</td>
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<tr>
<td>7</td>
<td>Runtime feature #6 / total number of arithmetic operations</td>
<td>47.5</td>
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<tbody>
<tr>
<td>1</td>
<td>Number of branches / number of statements</td>
<td>91.6</td>
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<tr>
<td>2</td>
<td>Scalar float operations / number of statements</td>
<td>75.8</td>
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<tr>
<td>4</td>
<td>OpenCL built-in functions / number of statements</td>
<td>66.9</td>
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<td>6</td>
<td>Scalar int operations / number of statements</td>
<td>56.6</td>
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<tr>
<td>7</td>
<td>Vector float operations / number of statements</td>
<td>52.2</td>
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<tr>
<td>8</td>
<td>Number of loops / number of statements</td>
<td>48.6</td>
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<tr>
<td>9</td>
<td>Scalar int operations</td>
<td>47.5</td>
</tr>
<tr>
<td>10</td>
<td>Scalar float operations</td>
<td>46.9</td>
</tr>
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<tbody>
<tr>
<td>3</td>
<td>Data transfer size for splittable buffer (host to device)</td>
<td>69.6</td>
</tr>
<tr>
<td>5</td>
<td>Data transfer size for splittable buffer (device to host)</td>
<td>64.0</td>
</tr>
</tbody>
</table>

An Automatic Input-Sensitive Approach for Heterogeneous Task Partitioning. Kofler, Grasso, Cosenza, Fahringer. ACM ICS 2013
Automatic Vectorization

```c
for (int i = 0; i < N; i++){
    a[i] = b[i] + k;
}
```
Automatic Vectorization

```c
for (int i = 0; i < N; i++){
    a[i] = b[i] + k;
}
```

x86-64 clang 5.0.0 -00
https://godbolt.org/g/orjryg

```assembly
mov dword ptr [rbp - 24], 0
.LBB0_1: # =>This Inner Loop Header: Depth=1
    cmp dword ptr [rbp - 24], 1024
    jge .LBB0_4
    # BB#2: # in Loop: Header=BB0_1 Depth=1
    mov rax, qword ptr [rbp - 16]
    movsx rcx, dword ptr [rbp - 24]
    movss xmm0, dword ptr [rax + 4*rcx] # xmm0=mem[0],0,0,0
    addss xmm0, dword ptr [rbp - 20]
    mov rax, qword ptr [rbp - 8]
    movsx rcx, dword ptr [rbp - 24]
    movss dword ptr [rax + 4*rcx], xmm0
    # BB#3: # in Loop: Header=BB0_1 Depth=1
    mov eax, dword ptr [rbp - 24]
    add eax, 1
    mov dword ptr [rbp - 24], eax
    jmp .LBB0_1

shufps xmm0, xmm0, 0 # xmm0 = xmm0[0,0,0,0]
    xor eax, eax
    .LBB0_5: # =>This Inner Loop Header: Depth=1
    movups xmm1, xmmword ptr [rsi + 4*rax]
    movups xmm2, xmmword ptr [rsi + 4*rax + 16]
    addps xmm1, xmm0
    addps xmm2, xmm0
    movups xmmword ptr [rdi + 4*rax], xmm1
    movups xmmword ptr [rdi + 4*rax + 16], xmm2
    movups xmm1, xmmword ptr [rsi + 4*rax + 32]
    movups xmm2, xmmword ptr [rsi + 4*rax + 48]
    addps xmm1, xmm0
    addps xmm2, xmm0
    movups xmmword ptr [rdi + 4*rax + 32], xmm1
    movups xmmword ptr [rdi + 4*rax + 48], xmm2
    add rax, 16
    cmp rax, 1024
    jne .LBB0_5
```

x86-64 clang 5.0.0 -03 (loop tail omitted)
https://godbolt.org/g/xttYbr
Vectorization Cost Modeling

- Automatic vectorization
  - From scalar to vector (packed) instructions

- Two approaches
  - Loop-level vectorization (LLV)
  - Superword Level Parallelism (SLP)

- Two questions
  - Is vectorization allowed?
  - Is vectorization beneficial?
    - Here good modeling is required

- Problem: predicting performance improvement (speedup) after vectorization
  - Used by loop vectorizer and SLP vectorizer
  - Solution: modeling as regression problem
Stencil Computation

- Example: six-point von Neumann stencil

```c
for(int t=1; t<nt; t++)
  for(int x=0; x<nx; x++)
    for(int y=0; y<ny; y++)
      for(int z=0; z<nz; z++)
      {
        out[x,y,z; t] =
        in[x-1,y,z; t-1] + in[x,y+1,z; t-1] +
        in[x+1,y,z; t-1] + in[x,y,z-1; t-1] +
        in[x,y-1,z; t-1] + in[x,y,z+1; t-1];
      }
```

For each time step $t$

For each cell $(x, y, z)$

One write: the element $(x, y, z)$ at time $t$

Some stencils have reads on older time steps: $t-2$, $t-3$, ...

We call the read-point pattern stencil shape
Stencil Code Tuning

- Tunable transformations in the Patus stencil compiler [Christen et al., SC 12]

```c
for(int t=1; t<nt; t++)
    for(int x=0; x<nx; x++)
        for(int y=0; y<ny; y++)
            for(int z=0; z<nz; z++)
            {
                out[x,y,z,t] =
                    in[x-1,y,z;t-1] + in[x,y+1,z;t-1] +
                    in[x+1,y,z;t-1] + in[x,y,z-1;t-1] +
                    in[x,y-1,z;t-1] + in[x,y,z+1;t-1];
            }
```

- **Blocking on** $(x,y,z)$
- **Unrolling** the innermost loop
- **Multi-threading + SIMD** (chunk number of consecutive tiles)
Stencil Auto-tuning

- Common approach: search-based iterative compilation
  - long compilation time for each code, but converges to a good solution
- Machine learning
  - machine-dependent model (in preprocessing phase)
  - then reuse it for new input stencil codes: fast compilation time
- Our approach: exploit structure of the problem (structural learning)
  1. Encode stencils and generate synthetic training set
  2. Build machine learning model using ordinal regression SVMs
  3. For new stencil code, use model to rank configurations and select best one
Stencil Encoding Example: Five-point Laplacian Stencil

- **Stencil features**
  - Shape
    
    ![Stencil Diagram]
    
    \[
    \begin{bmatrix}
    p(-1,1) & p(0,1) & p(1,1) \\
    p(-1,0) & p(0,0) & p(1,0) \\
    p(-1,-1) & p(0,-1) & p(1,-1)
    \end{bmatrix}
    \rightarrow
    \begin{bmatrix}
    0 & 1 & 0 \\
    1 & 1 & 1 \\
    0 & 1 & 0
    \end{bmatrix}
    \]
  
  - Number of buffers
  
  - Data type (0 for float, 1 for double)
  
  - Input size

- **Tuning features**
  
  - Blocking size
  
  - Chunking size
  
  - Unrolling factor
Synthetic Training Set Generation

- A code generator generates stencil codes with different
  - shapes: line, hyperplane, hypercube and Laplacian
  - number of buffers
  - buffer types
- The generated stencil codes are executed with different
  - input sizes
  - tuning parameters
Modeling with Ordinal Regression

- **Classification**
  - Training set in terms of classes
  - Problem with large transformation space

- **Regression**
  - Training set as numerical performance values
  - Difficult problem: performance prediction

- **Ordinal Regression**
  - Training set as partially ordered set
  - Prediction through ranking function
  - We select the top-ranked transformation
Training Set as Rankings

- The training set arranged in terms of (partial) rankings
- From ranking to inequalities
  - transitive inequalities are omitted

<table>
<thead>
<tr>
<th>Execution</th>
<th>Input</th>
<th>Tuning</th>
<th>Runtime</th>
<th>Rank</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>$q_1 = (k_1, s_1)$</td>
<td>$t_{e_1}$</td>
<td>12ms</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>$q_1 = (k_1, s_1)$</td>
<td>$t_{e_2}$</td>
<td>13ms</td>
<td>2</td>
</tr>
<tr>
<td>3</td>
<td>$q_1 = (k_1, s_1)$</td>
<td>$t_{e_3}$</td>
<td>20ms</td>
<td>3</td>
</tr>
<tr>
<td>4</td>
<td>$q_2 = (k_1, s_2)$</td>
<td>$t_{e_4}$</td>
<td>10ms</td>
<td>1</td>
</tr>
<tr>
<td>5</td>
<td>$q_2 = (k_1, s_2)$</td>
<td>$t_{e_5}$</td>
<td>36ms</td>
<td>3</td>
</tr>
<tr>
<td>6</td>
<td>$q_2 = (k_1, s_2)$</td>
<td>$t_{e_6}$</td>
<td>35ms</td>
<td>2</td>
</tr>
<tr>
<td>7</td>
<td>$q_3 = (k_2, s_1)$</td>
<td>$t_{e_7}$</td>
<td>30ms</td>
<td>1</td>
</tr>
<tr>
<td>8</td>
<td>$q_3 = (k_2, s_1)$</td>
<td>$t_{e_8}$</td>
<td>45ms</td>
<td>2</td>
</tr>
<tr>
<td>9</td>
<td>$q_3 = (k_2, s_1)$</td>
<td>$t_{e_9}$</td>
<td>47ms</td>
<td>3</td>
</tr>
<tr>
<td>10</td>
<td>$q_4 = (k_2, s_2)$</td>
<td>$t_{e_{10}}$</td>
<td>25ms</td>
<td>3</td>
</tr>
<tr>
<td>11</td>
<td>$q_4 = (k_2, s_2)$</td>
<td>$t_{e_{11}}$</td>
<td>21ms</td>
<td>2</td>
</tr>
<tr>
<td>12</td>
<td>$q_4 = (k_2, s_2)$</td>
<td>$t_{e_{12}}$</td>
<td>12ms</td>
<td>1</td>
</tr>
</tbody>
</table>

Stencil instance: kernel shape + sizes
Tuning setting (unroll factor, block size, chunk)
Ordinal Regression with Structural SVMs

- Let us represent with $r^*$ the real ranking in the training set
  - Given $\tau$, which measures the error between the assigned ranking and the real ranking, we can formalize our problem as
    \[
    \min_{r_i \in Q} \sum_{q_i \in Q} \tau_{q_i}(r, r^*)
    \]
- The learning problem can be solved using structural Support Vector Machines
  - Little training time [T. Joachim, KDD 2002]

\[
\begin{align*}
\min_{w, \xi \geq 0} & \frac{1}{2} w^T w + \frac{C}{m} \sum_{(i,j) \in P} \xi_{i,j} \\
\text{subject to} & \forall (i, j) \in P : (w^T q_i, t_i) \geq (w^T q_j, t_j) + 1 - \xi_{i,j}
\end{align*}
\]
Ordinal Regression with Partial Ranking

- **Problem**: we have only partial ranking
  - we cannot compare stencil executions with different stencil kernel \( k \) or size \( s \)
  - we have full ranking only for subsets of \( P \)

- **Solution**
  - Let us assume that \( P_i \subseteq P \) as the set of inequalities generated by the instance \( q_i \)
  - Assuming that \( P_1, P_2 \cdots P_n \) are all partial rankings available in the training set, we modify the previous equation:

\[
\min_{w, \xi \geq 0} \frac{1}{2} w^T w + \frac{C}{m'} \sum_{i} \sum_{(j,k) \in P_i} \xi_{j,k}
\]

subject to:
\[
\forall (j, k) \in P_1 : (w^T q_1, t_j) \geq (w^T q_1, t_k) + 1 - \xi_{j,k}
\]
\[
\forall (j, k) \in P_2 : (w^T q_2, t_j) \geq (w^T q_2, t_k) + 1 - \xi_{j,k}
\]
\[
\cdots
\]
\[
\forall (j, k) \in P_n : (w^T q_n, t_j) \geq (w^T q_n, t_k) + 1 - \xi_{j,k}
\]

where \( m' = |\bigcup_i P_i| \) and \( n = |Q| \)
Autotuning with Ordinal Regression
Quality of the Top-ranked version

- Good results also with small training dataset
  - with 8K-point dataset, 15 of 17 benchmarks performs >90% than an iterative-search approach

- Larger training dataset increase the ability of the model to correctly rank code versions
  - Kendall’s Tau distribution

- Promising approach: can be applied to other tuning problems
  - as soon as code variants can be organized as partial rankings
Ranking Evaluation: Kendall’s τ

- How to evaluate whether a ranking is good?
- Kendall’s τ coefficient
  - Given two finite orderings \( r_a, r_b \subset Q \times Q \), where \( Q \) is the set of all stencil instances
  - τ value
    - 1, perfect agreement between \( r_a \) and \( r_b \)
    - 0, whether \( r_a \) and \( r_b \) are independent
    - -1, perfect disagreement between \( r_a \) and \( r_b \) (ranking in perfect reverse order)

\[
\tau(r_a, r_b) = \frac{Con - Dis}{Con + Dis} = 1 - \frac{2Dis}{\binom{m}{2}}
\]

**Con** concordant pairs
**Dis** discordant pairs (inversions)
Results
Ranking Evaluation with Kendall’s $\tau$ Values

- The Kendall $\tau$ values on the training dataset, for two different training set sizes

![Graph of Kendall's $\tau$ values for size=960](image1)

![Graph of Kendall's $\tau$ values for size=6720](image2)
Results
Ranking Evaluation with Kendall’s $\tau$ Values

- The Kendall $\tau$ values with different training set sizes

Machine learning with Auto-tuning

- Interesting for portability and integration into compilers

- Challenges
  - Applications
  - Training data availability
  - Input encoding
  - Modeling

- Some interesting solutions
  - Automatic synthetic training data generation
    - Domain-specific code generation [Cosenza et al., IPDPS 2017]
    - Generic synthesis approaches [Cummins et al., PACT 2017; CGO 2017]
  - Kernel functions
  - Structural learning
Programming Models & Tuning

The (parallel) programming model matter

- Library
  - GROMACS parallelization
  - SCALAPACK
- Domain-specific Languages
  - Patus stencil compiler
  - OpenGL Shading Language
- Annotated C program
  - OpenMP
  - OpenACC
- C program
  - Automatic vectorization

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Programming Models & Tuning

- Interaction between high-level and low-level tuning
  - High-level tuning
    - Algorithm choices
    - Mapping, scheduling, parallelism granularity
    - Spatial data structures
  - Low-level tuning
    - Tiling, unrolling, vectorization

- Ongoing research
  - OpenABL: a domain-specific language for agent-based simulation
    - Target: multi-core CPU, GPU, cluster
  - CELERITY: extension of SYCL with compiler, runtime system and modeling
    - Target: High Performance Computing
    - Funded by DFG
Thanks for your attention

Auto-tuning Compiler Transformations with Machine Learning

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